

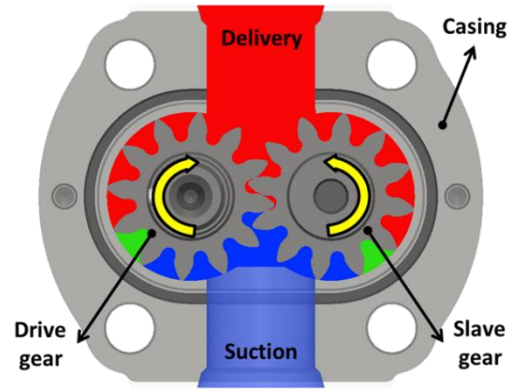
A model-based approach for the evaluation of noise emissions in external gear pumps

Sangbeom Woo

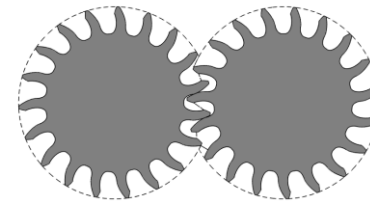
6/4/2019

- Introduction
- Modeling Details & Experimental Setup
- Numerical & Experimental Results
- Model Potentials

- Noise is a key issue for current hydraulic systems and limiting factor to the spread of hydraulics into new fields
- Displacement machines are the primary sources of noise in fluid power systems
- Reference: External Gear Pumps



- Successful design solutions involving gears focusing on flow oscillations:
 - Negrini (1996) – Dual-flank gears
 - Fiebig (2010) – Compression filter volumes
 - Mucchi (2010) – Split gear solution
 - Lätzel (2012) – Cycloidal gear profiles
 - Morselli (2015) – Helical asymmetric gears

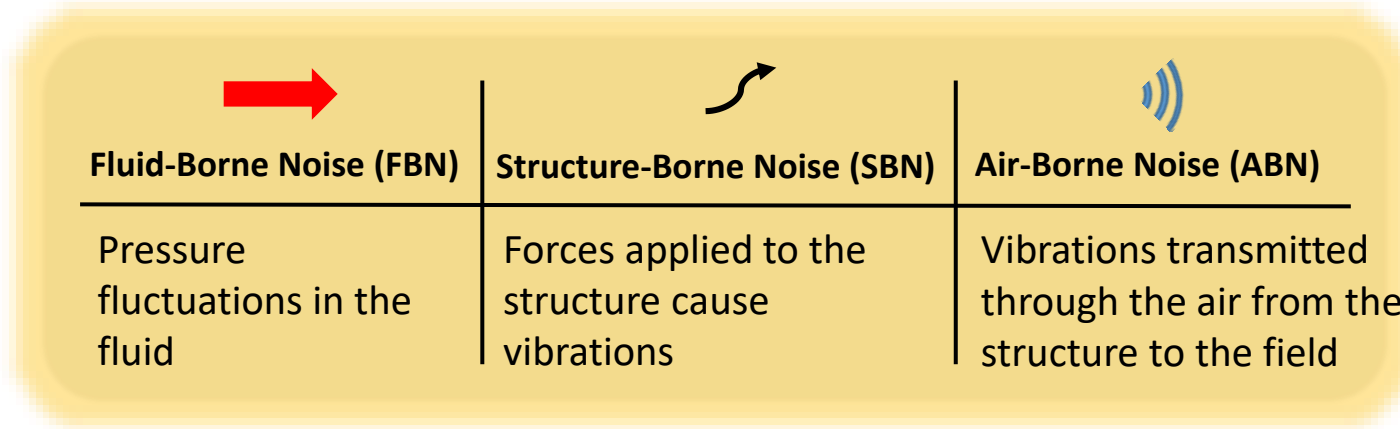
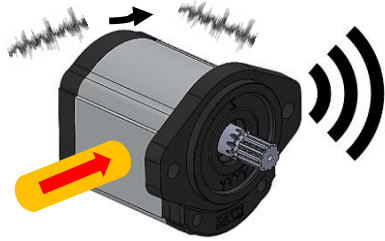


Asymmetric gears



Helical gears

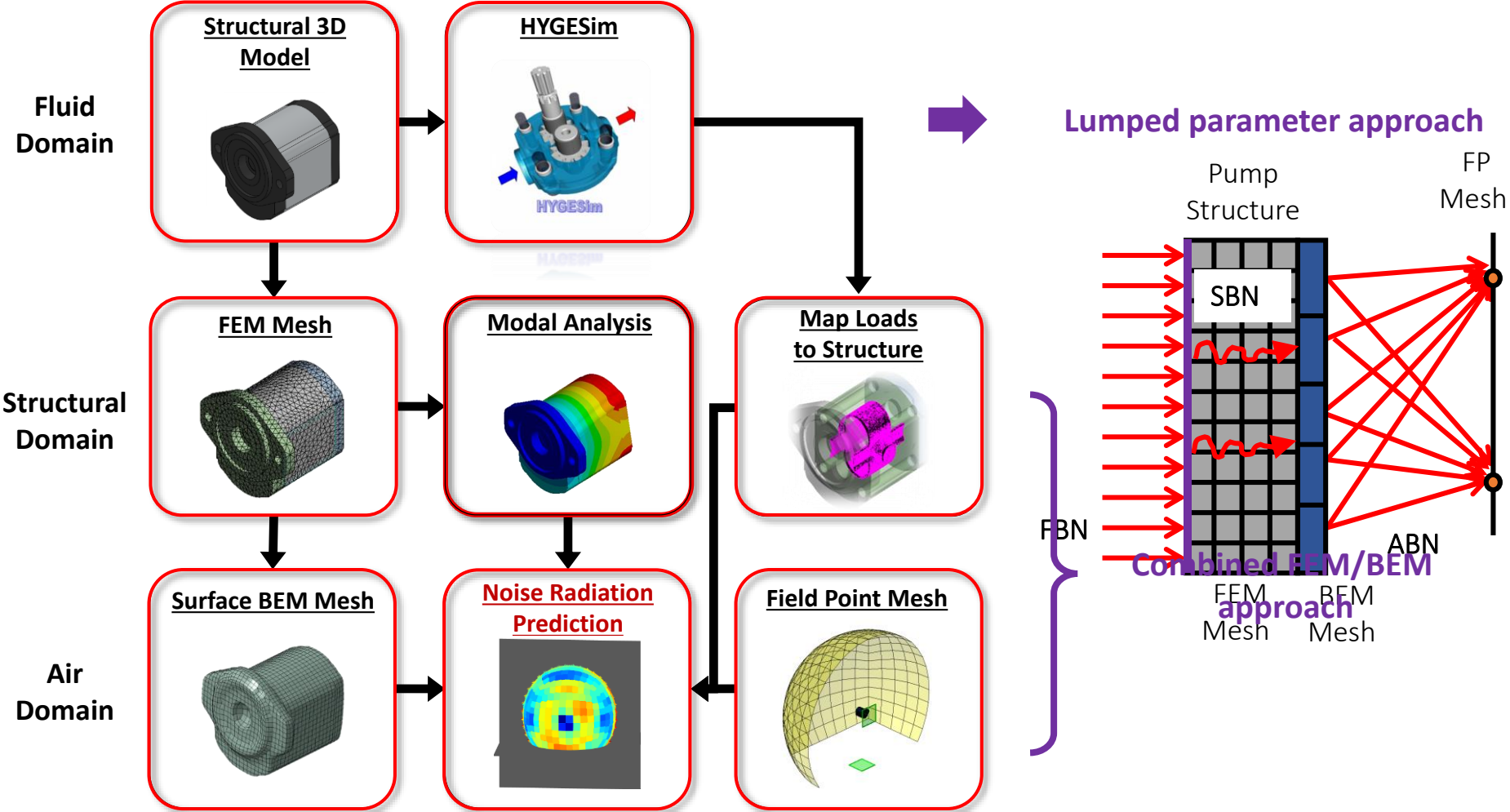
- All sources of noise and how noise propagates through the system are not well understood
- Noise generation in external gear pumps involves **three domains**



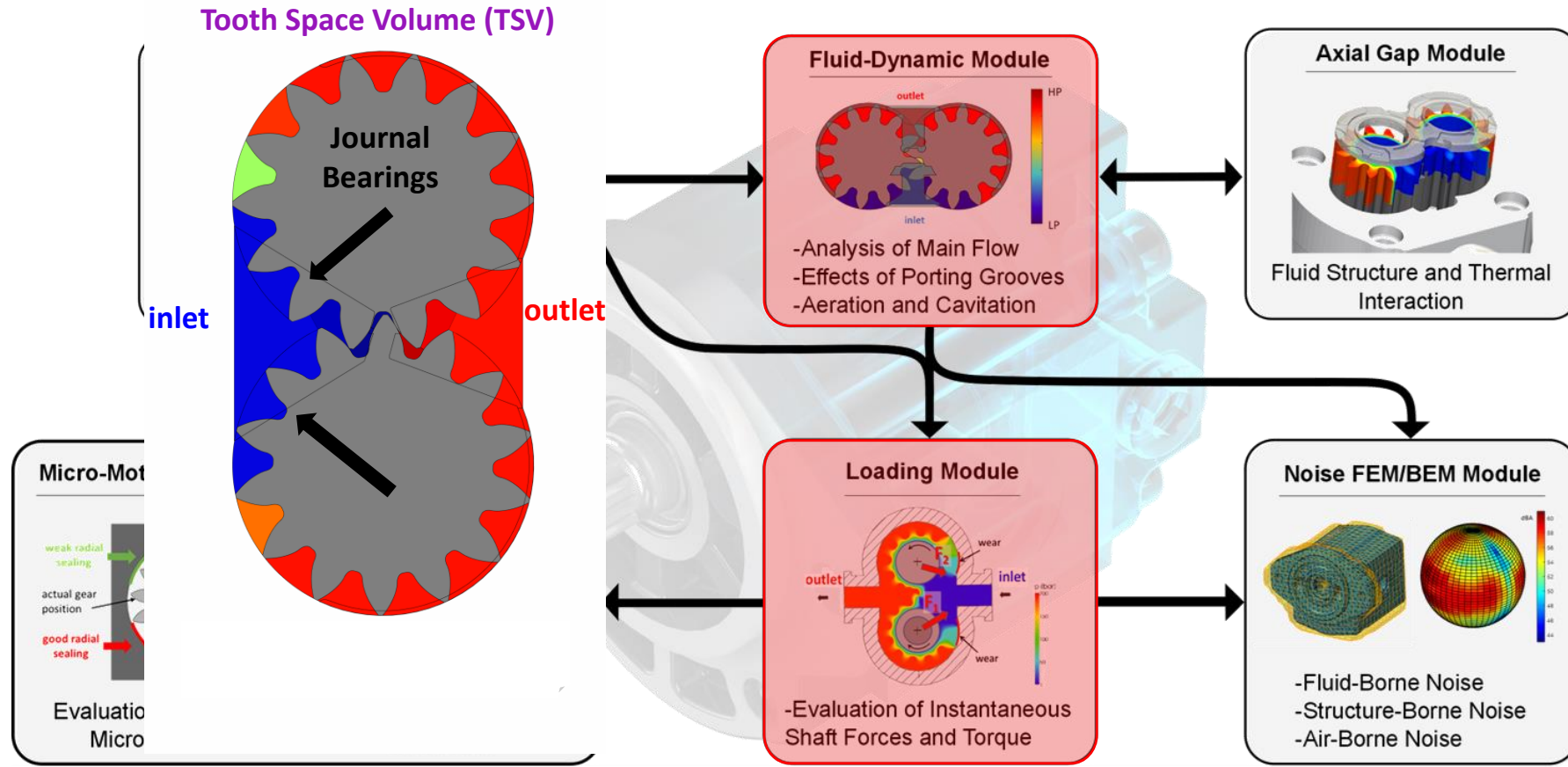
Aims of the research:

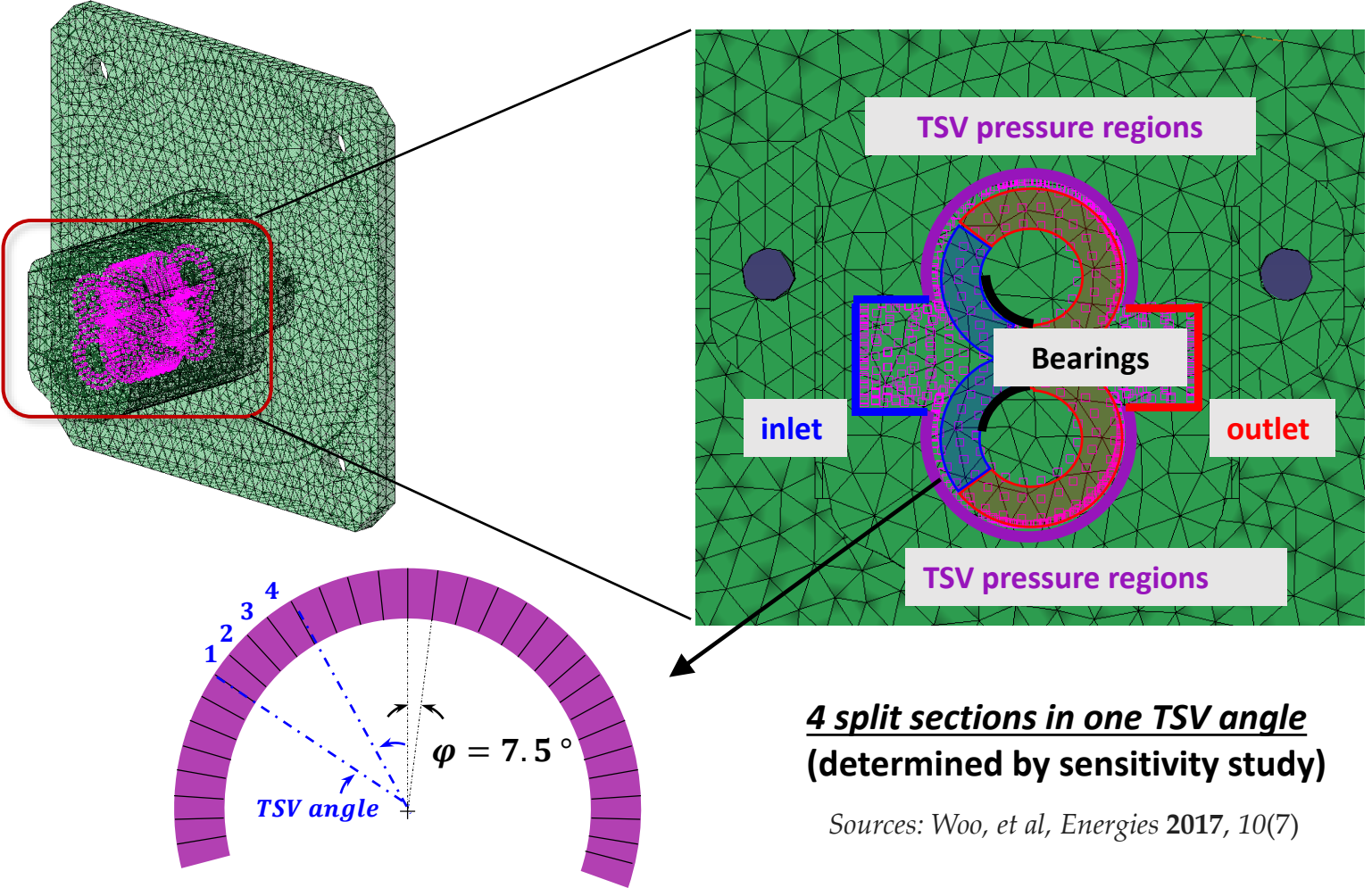
- Develop the noise prediction model which considers all possible noise sources and interaction between three domains
- Identify the effect of the pump mounting conditions on the emitted noise in the numerical modeling works

Simulation Model Structure



HYGESim

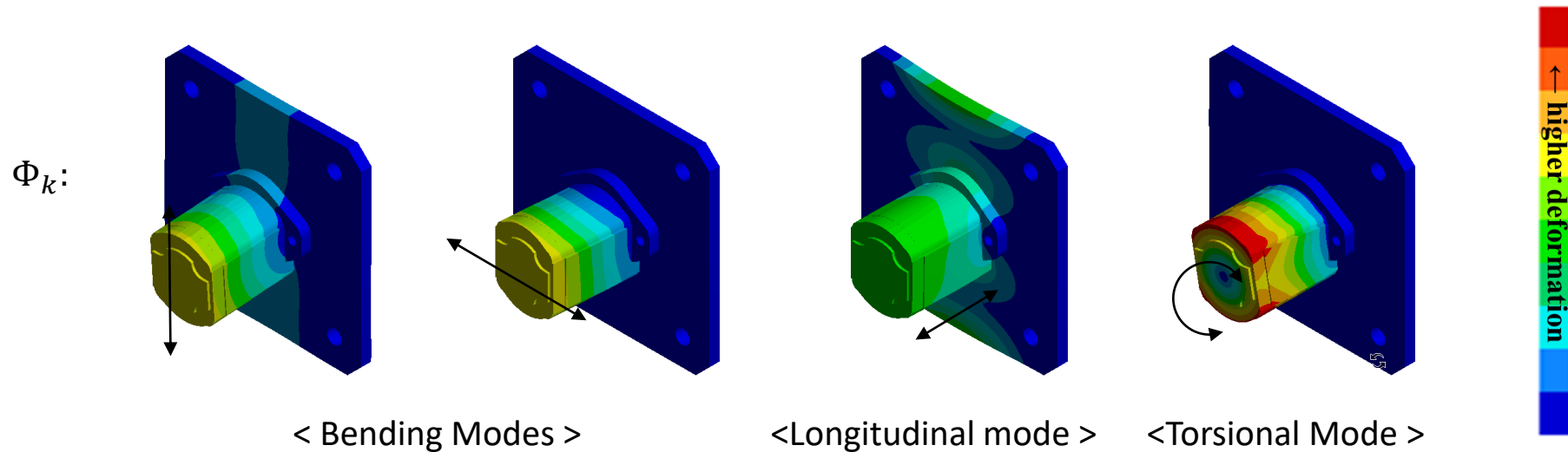




4 split sections in one TSV angle
(determined by sensitivity study)

Sources: Woo, et al, Energies 2017, 10(7)

- Numerical Modal Analysis
 - Modes in the audible frequency (20 Hz ~ 20 kHz) are considered



- Modal superposition technique** is used to determine the structural forced response

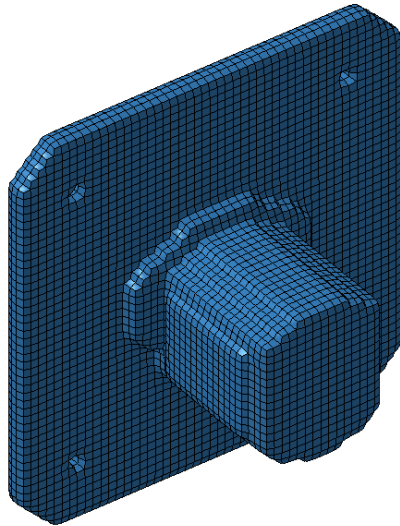
$$\{w\} = \sum_{k=1}^M q_k \Phi_k = [\Phi] \cdot \{q\}$$

w : Displacement (Forced response of structure)

q_k : Modal participation factors

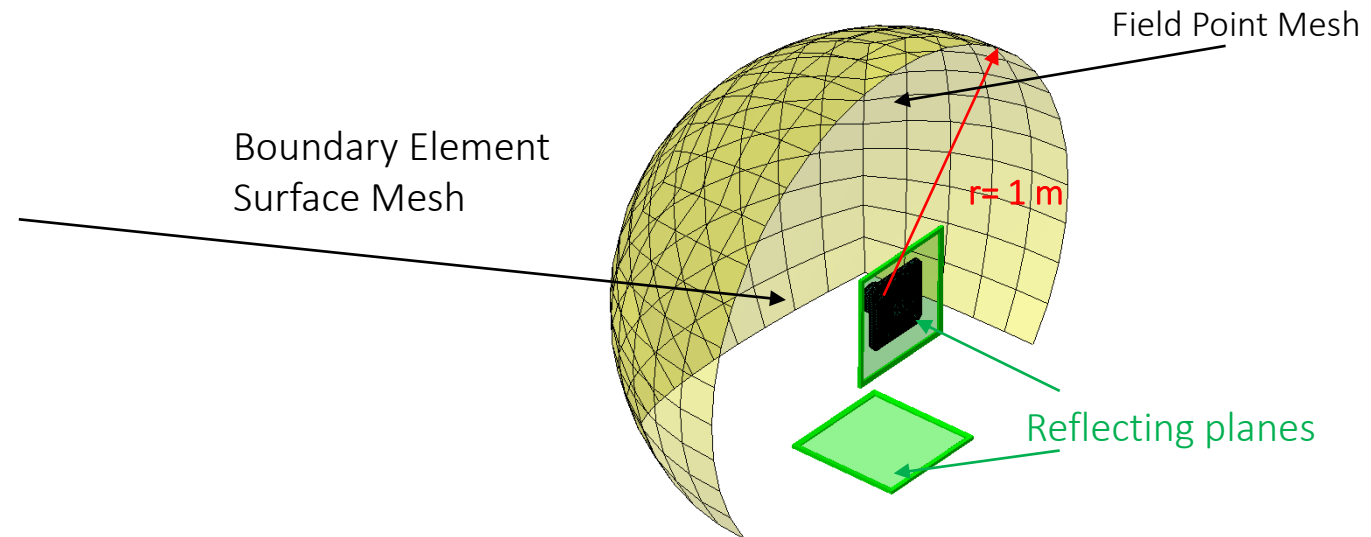
Φ_k : Modal vectors (mode shapes)

■ Boundary Element Surface Mesh

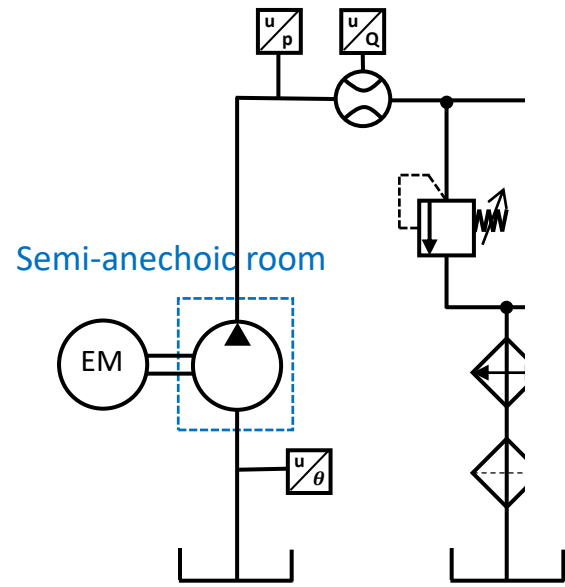


- Generated on the exterior surface of FEM Mesh
- Uniformly distributed coarsened mesh for efficient calculation

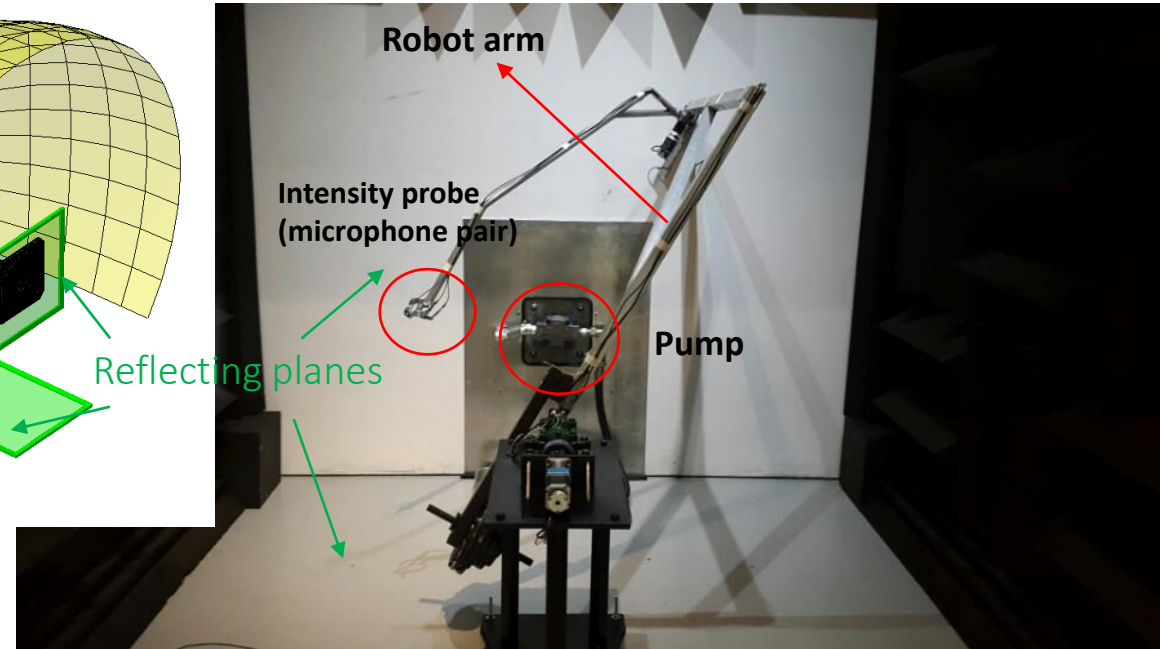
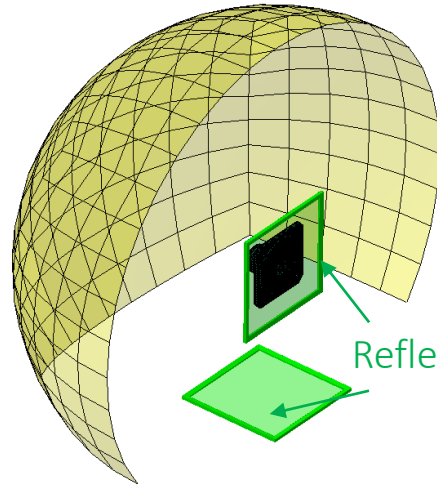
■ Field Point Mesh & Acoustic Environments



- Visualization mesh in acoustic domain
- Can be regarded as microphone arrays
- Mimic the acoustic environments of semi-anechoic chamber



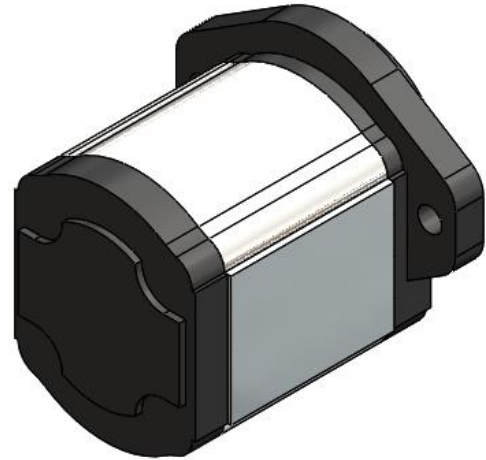
<Anechoic chamber test rig hydraulic schematic>



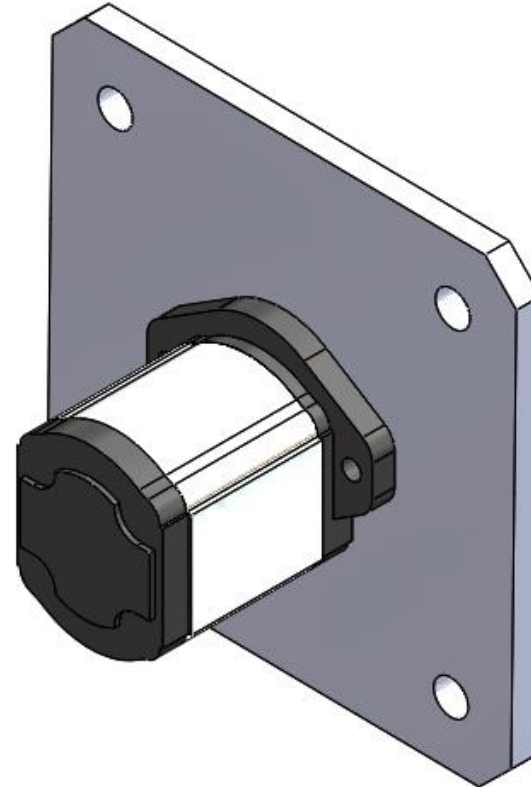
ISO 9614-1 (Acoustics—
Determination of Sound Power
Levels of Noise Sources using Sound
Intensity. Part 1: Measurement at
Discrete Points)

- The inlet temperature was kept constant (Steady-state conditions)
- Sound intensity was measured at discrete points using the robot arm

- Standalone Pump



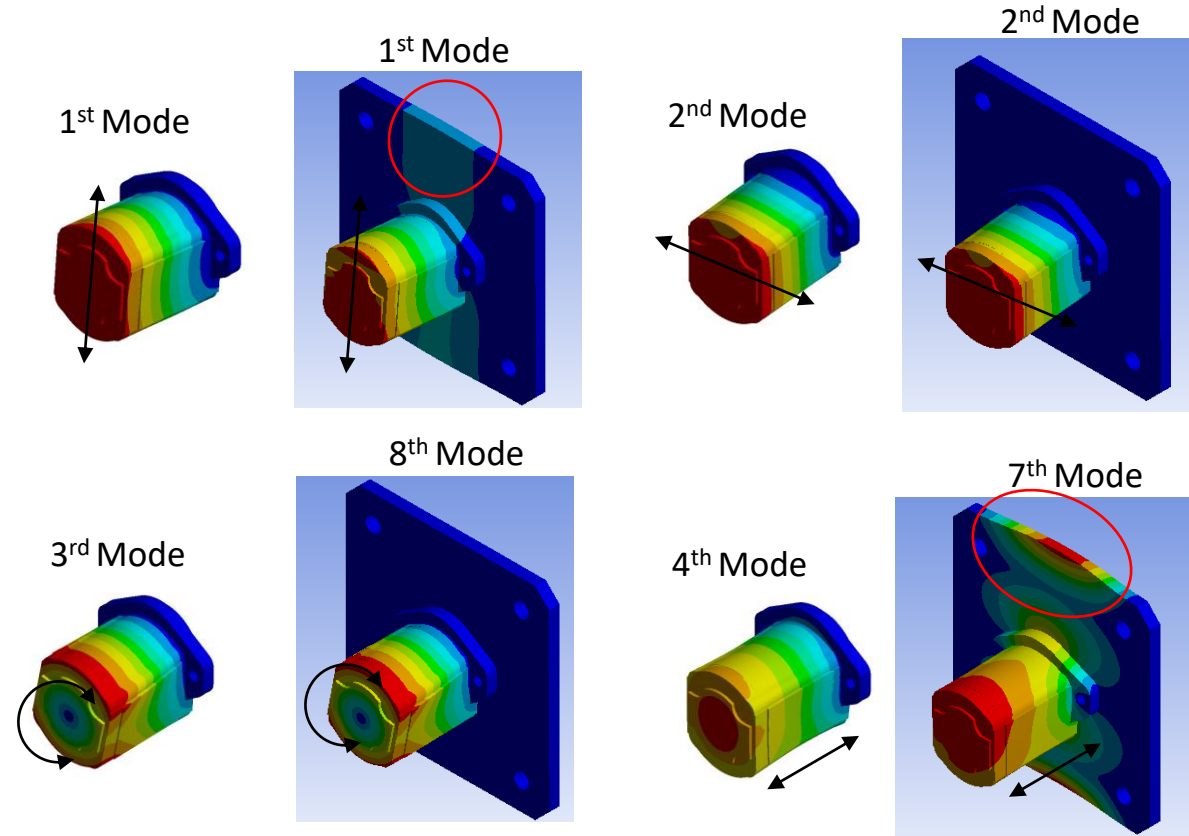
- Pump with structure



Modal Analysis Results

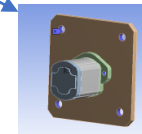
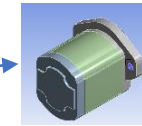
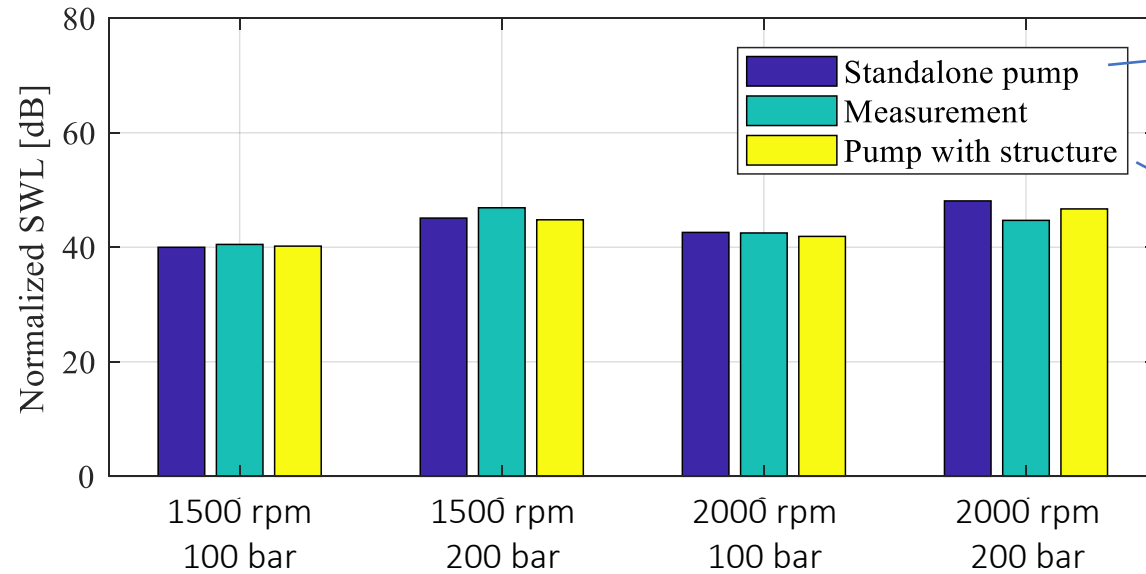
*(Reference of normalization:
1st numerical modal frequency of standalone pump)*

Mode	Standalone	with structure
	Normalized Frequency	
1	1.00	0.58
2	1.02	0.91
3	1.95	1.00
4	2.75	1.07
5	3.71	1.34
6	3.89	1.37
7	5.18	1.74
8	5.43	1.93
9	5.60	2.27
10	5.72	2.30
11	5.85	2.34
12	6.27	2.37
13	6.36	2.60
14	6.60	0.72
15	6.94	3.02
16	7.04	3.16
17		3.34
18		3.47
19		3.47
20		3.67



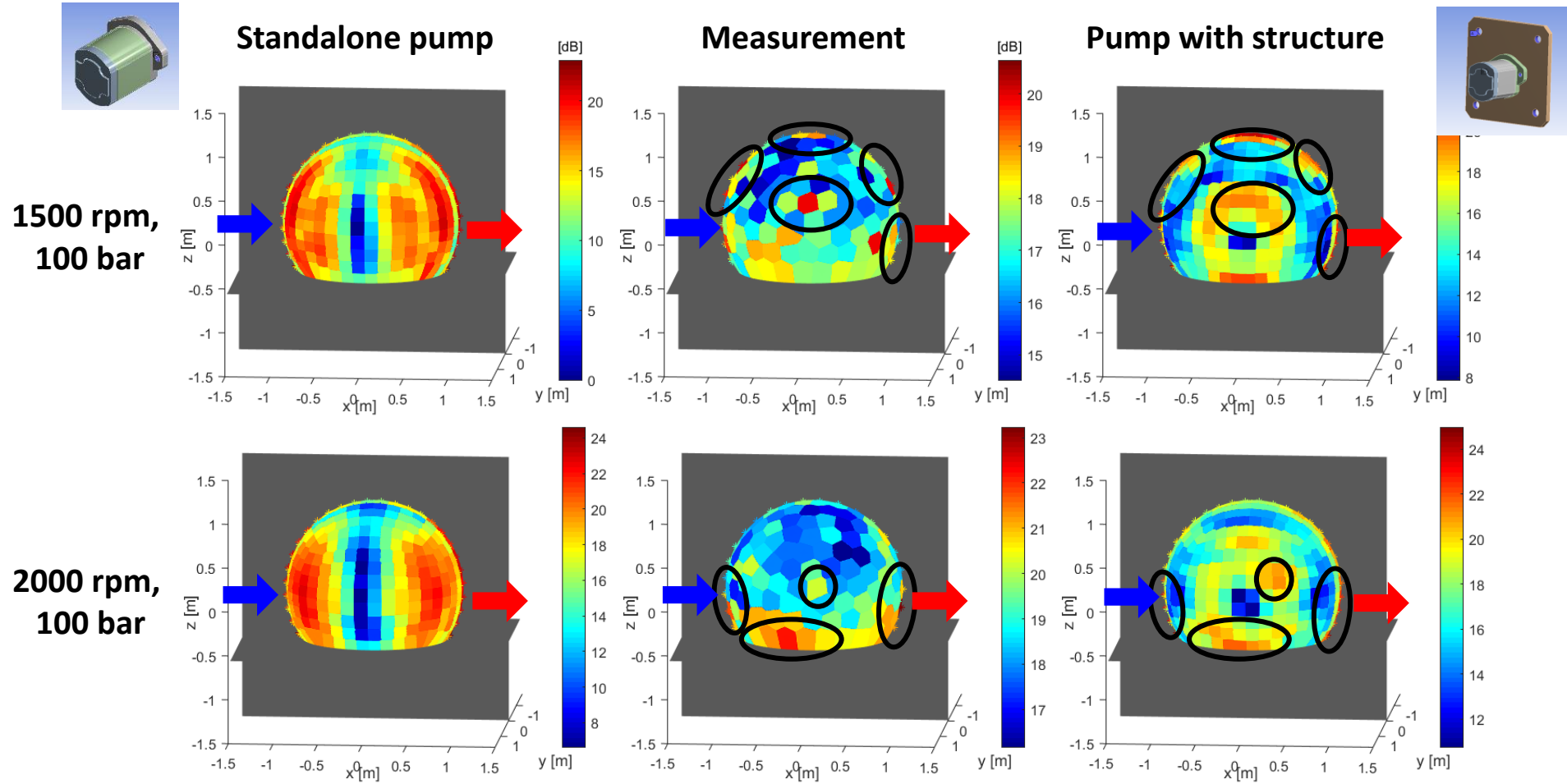
- Including structures lower the first resonant frequency
- Some mode shapes contain the axial motion of the plate

(Reference of normalization:
Sound power of the experimental noise floor)

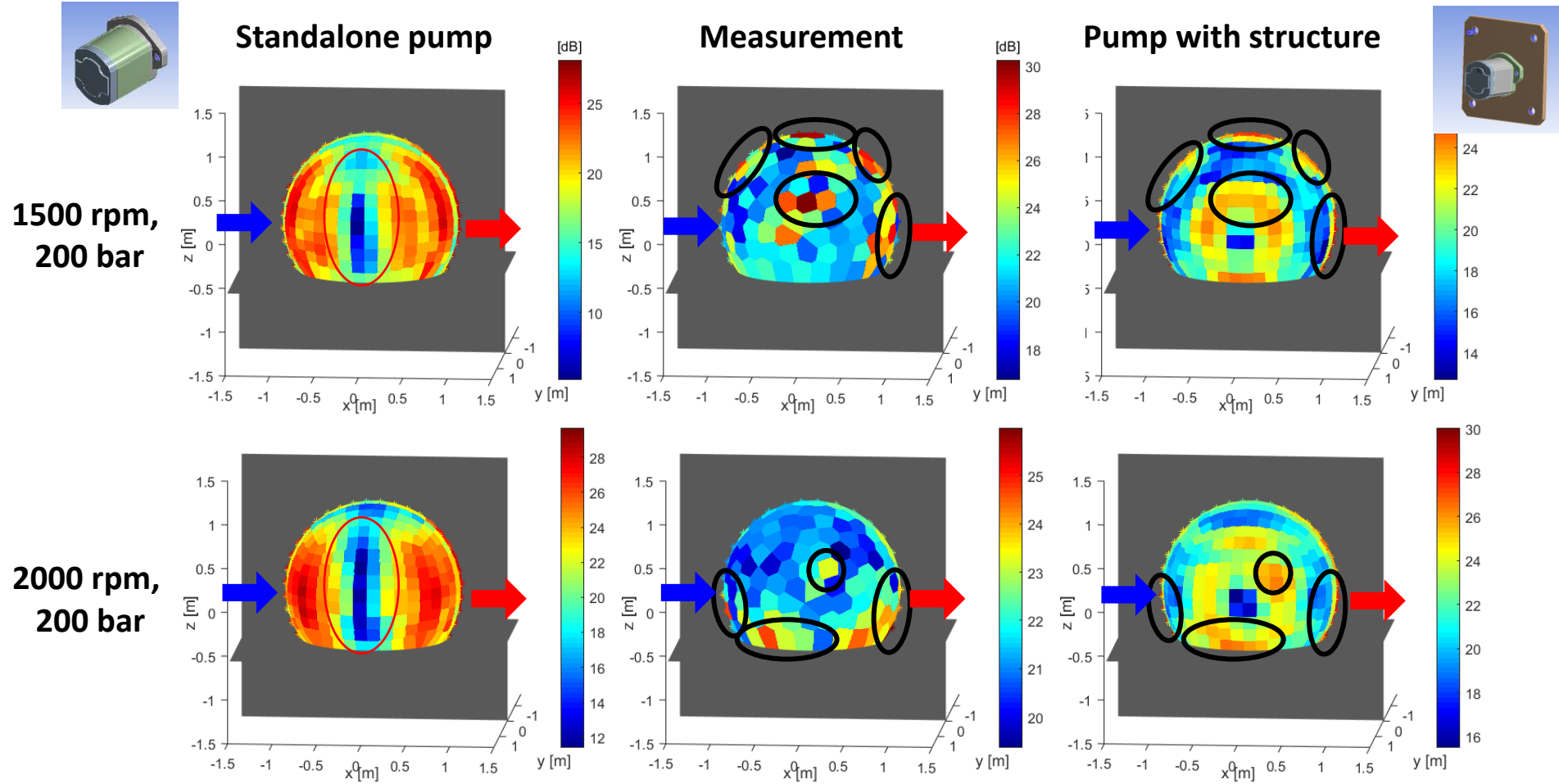


Operating conditions	Standalone pump	Measurement	Pump with structure
1500 rpm, 100 bar	40.0 dB (-0.5 dB)	40.5 dB	40.2 dB (-0.3 dB)
1500 rpm, 200 bar	45.1 dB (-1.8 dB)	46.9 dB	44.8 dB (-2.1 dB)
2000 rpm, 100 bar	42.6 dB (+0.1 dB)	42.5 dB	41.9 dB (-0.6 dB)
2000 rpm, 200 bar	48.1 dB (+3.4 dB)	44.7 dB	46.7 dB (+2.0 dB)

- the range of discrepancy becomes smaller ([-1.8~3.4 dB] → [-2.1~2.0 dB])



- By including structures, the acoustic model starts to capture the noisy areas

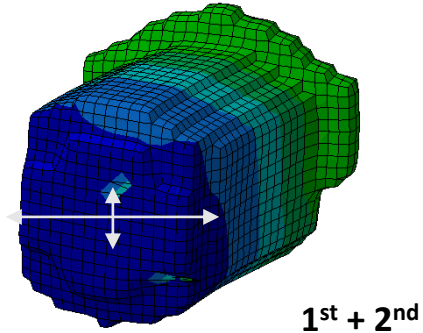


- Noisy areas remain almost the same at the same shaft speed

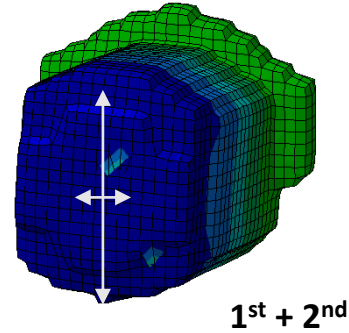
Vibration of 'standalone pump'

- Forced response of the structure (Displacement)

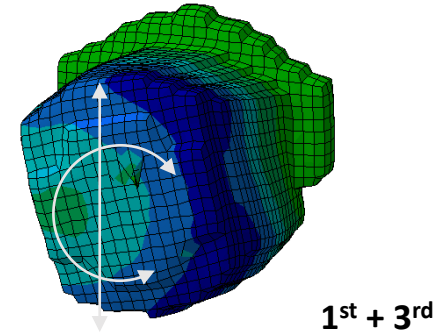
600 Hz (2nd harmonic)



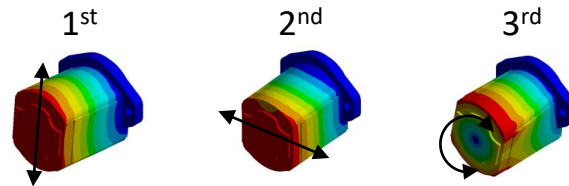
2700 Hz (9th harmonic)



4500 Hz (15th harmonic)



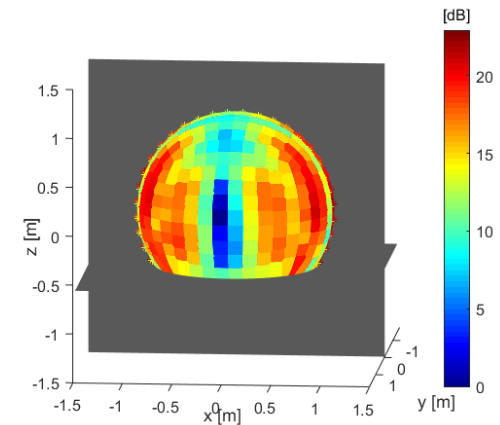
- All the motions appear to be the superposition of 1, 2, and 3 mode shapes



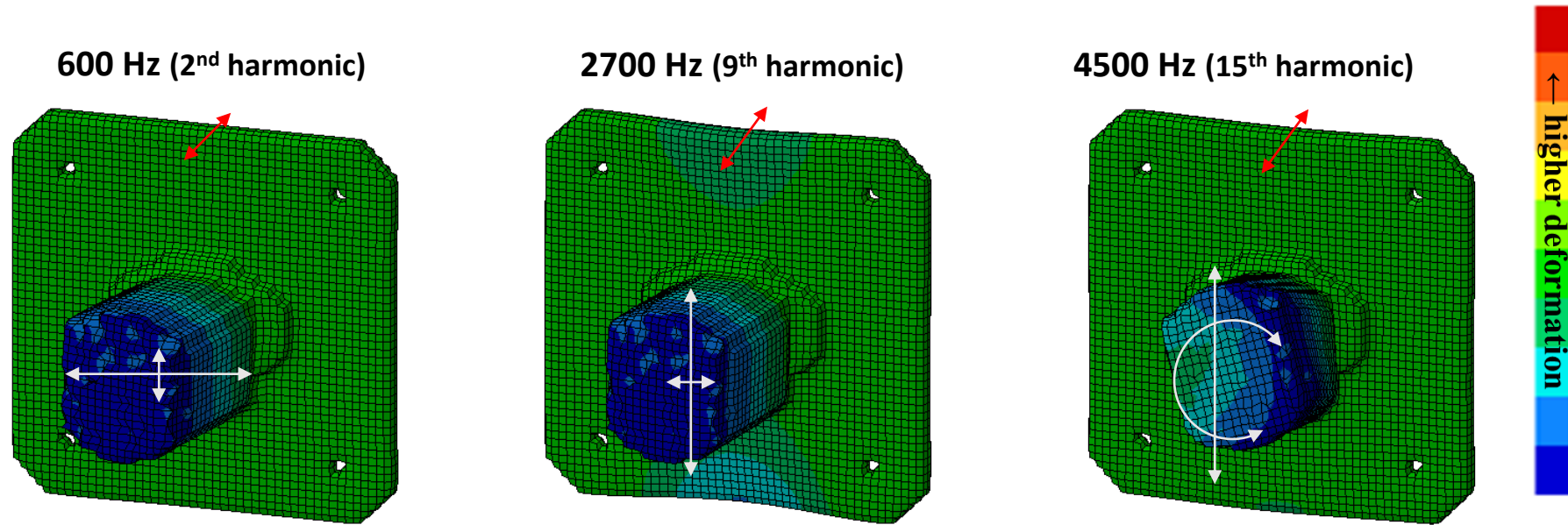
- No axial motions are observed at all frequencies up to 5 kHz
- Low noise emission in axial direction



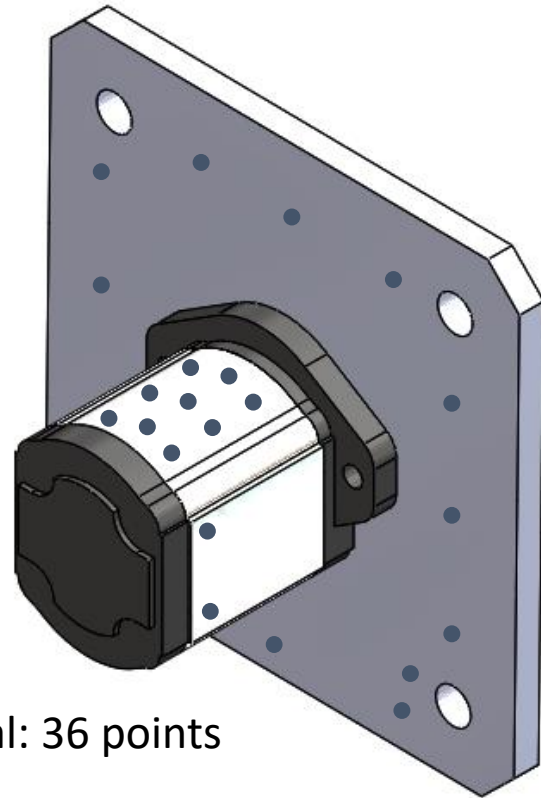
Limitations of the standalone pump model



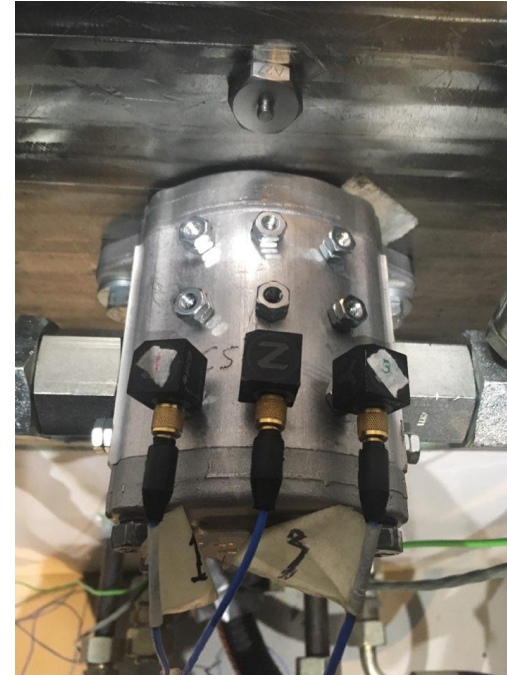
Vibration of 'pump with structures'



- Vibrations of the pump are similar to those of the standalone pump
- Vibrations of plate in axial direction also can be observed
- It can contribute to noise emissions in axial directions

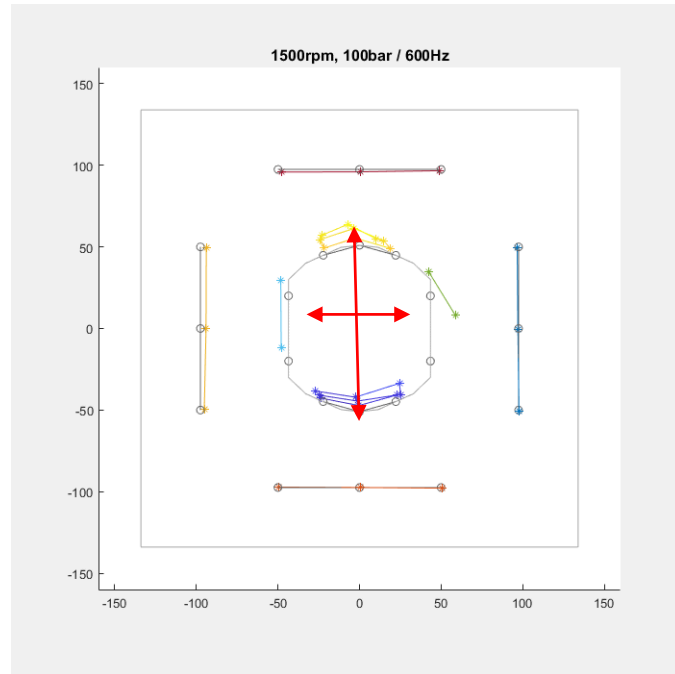
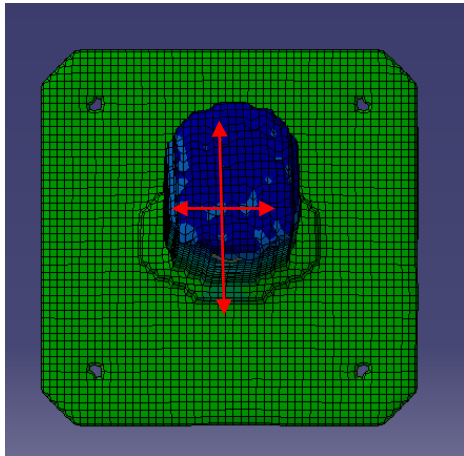


Total: 36 points

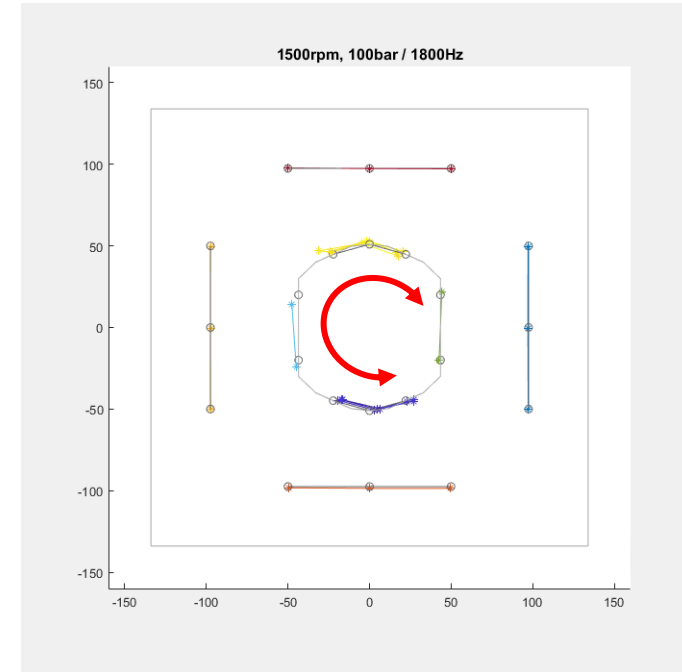
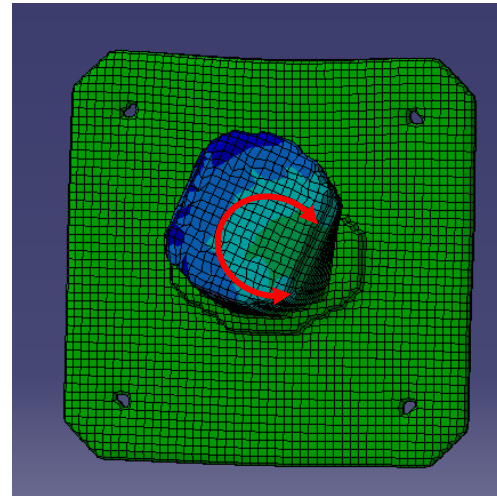


- Accelerometers were mounted to pump and plate during the pump operation
- Acceleration signals were synchronized using cross-correlation

< Bending Motion >



< Torsional Motion >

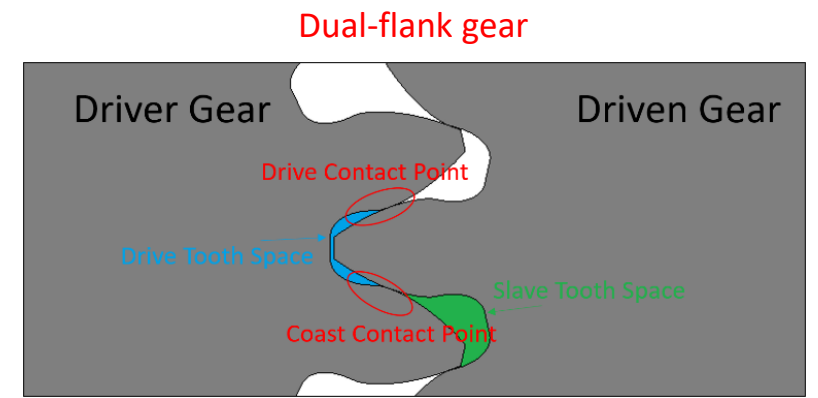
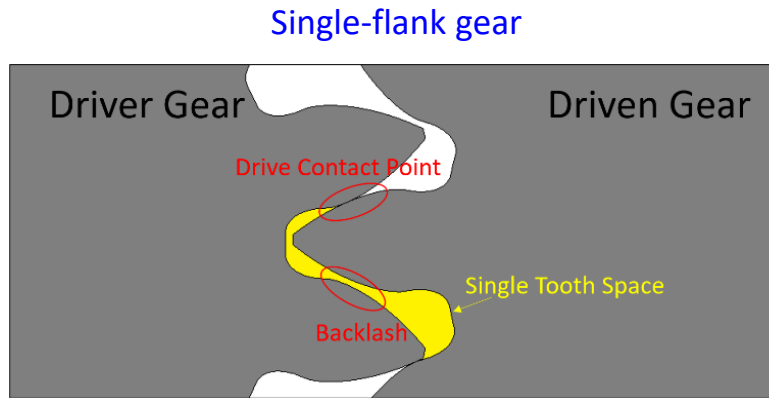


- Vibration prediction using modal superposition technique is valid
- Vibration of the plate can be observed in the measurement

- Considered two different gears designed to fit into the same housing

Sources: Woo, et al, BATH/ASME FPMC 2017

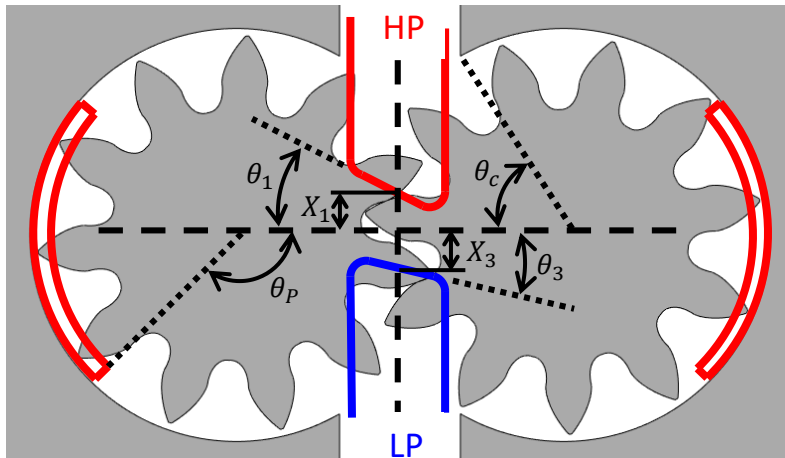
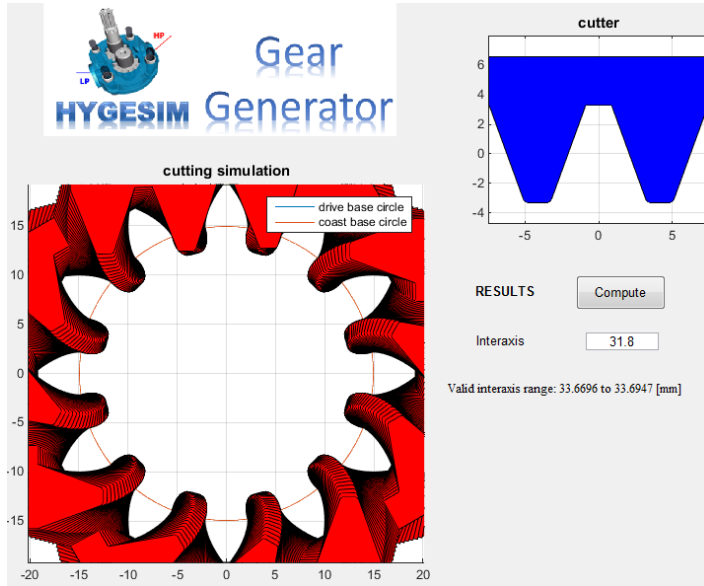
- Displacement: 24 cc/rev
- Number of teeth: 14
- Pressure angle: 20 °
- Center distance: 35 mm



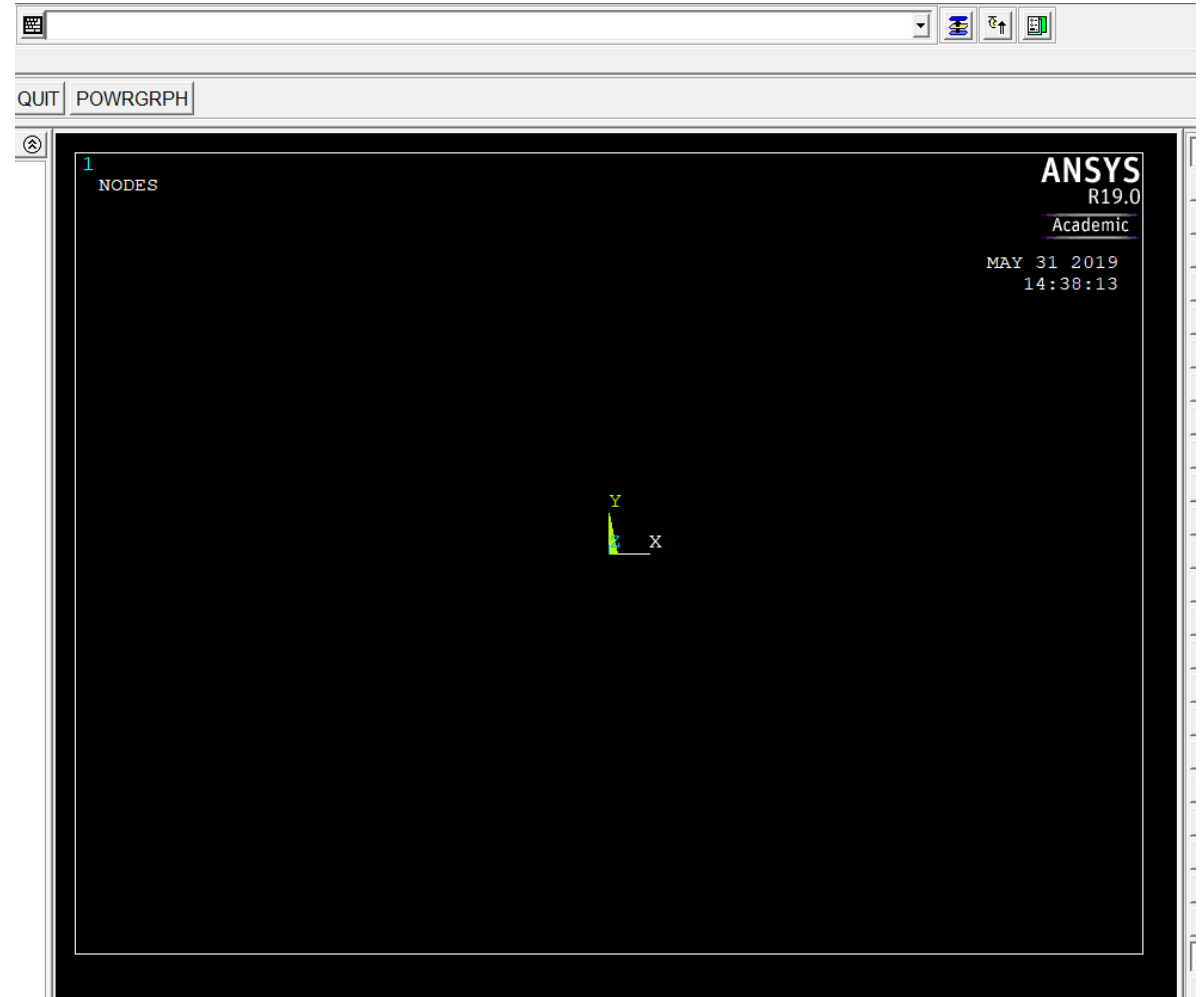
Overall SWL [dB]	Dual-flank		Single- flank	Difference
1000 rpm, 50 bar	71.9 dB	<	74.3 dB	2.4 dB
1000 rpm, 100 bar	73.5 dB	<	75.4 dB	1.9 dB

Acoustic model confirmed lower noise level of the dual-flank design

- Gear & Groove Design Parameters



- Parameterization of acoustic model for optimization



- Objective function: Sound Power

Thank you. Questions?